SERVICE MANUAL

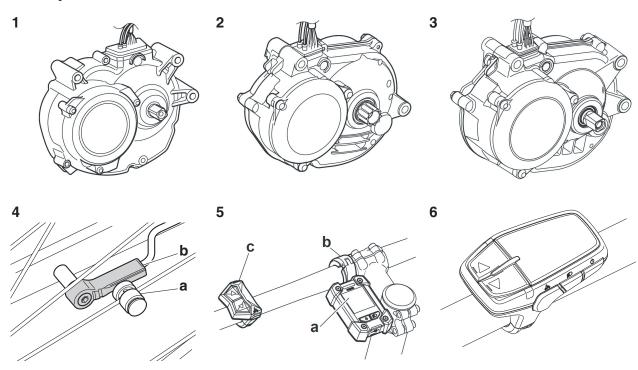
e-Bike SYSTEMS Drive Unit and Display

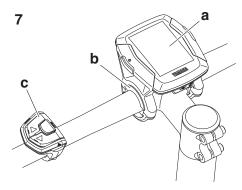
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General Information

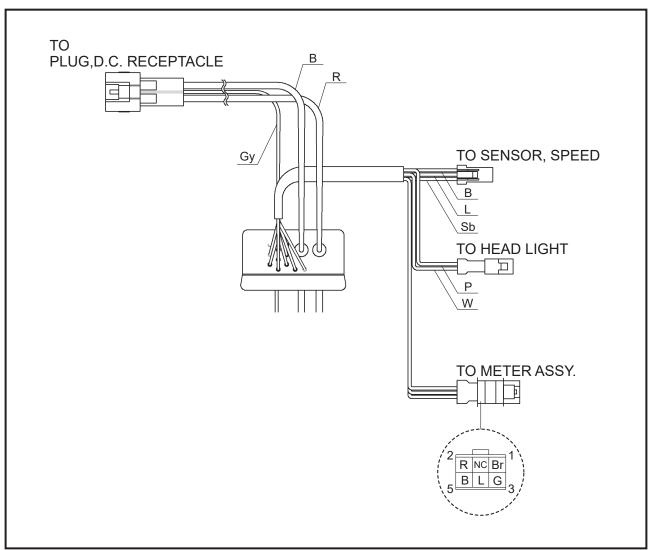
Description





- 1. Drive Unit (PWseries SE)
- 2. Drive Unit (PW-X)
- 3. Drive Unit (PWseries TE)
- 4. Speed sensor set
 - a) Magnet sensor spoke type
 - b) Pick up
- 5. Display unit (Display X)
 - a) Display
 - b) Clamp
 - c) Switch
- 6. Display unit (Display A)7. Display unit (Display C)
 - a) Display
 - b) Clamp
 - C) Switch

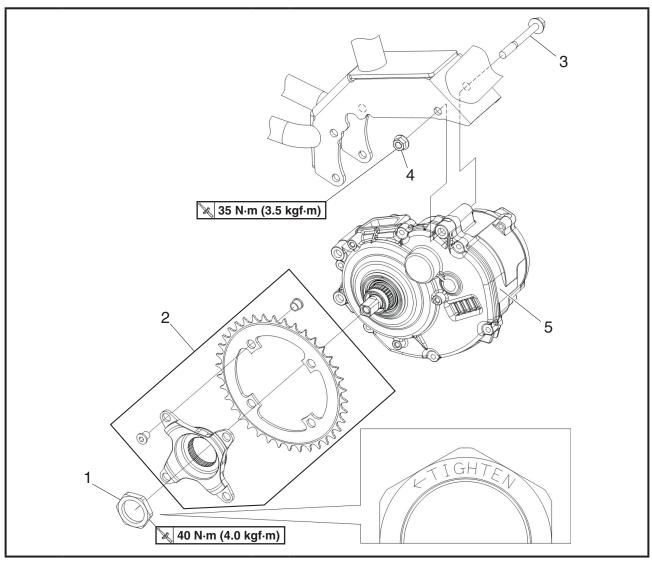
Installation <PWseries SE, PW-X, PWseries TE> Electrical component wiring diagram



 $\begin{array}{lll} B &= Black & P &= Pink \\ Br &= Brown & R &= Red \\ G &= Green & Sb &= Sky blue \\ Gy &= Gray & W &= White \\ L &= Blue & Y &= Yellow \end{array}$

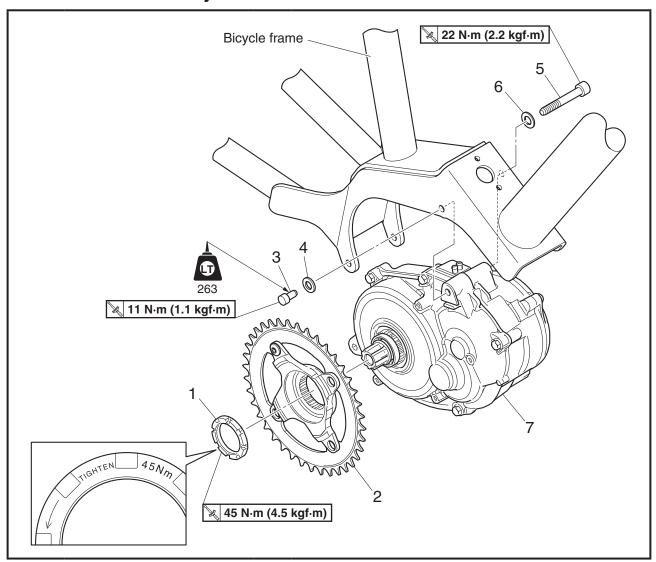
Or = Orange

<PWseries SE> Drive Unit assy.

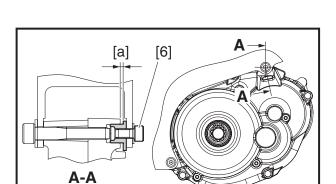


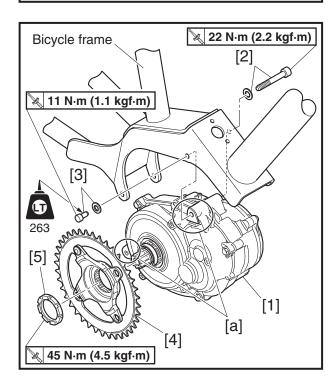
Order	Job/Part	Q'ty	Remarks
	Removal of the Drive Unit		Follow the work procedures for removal.
	assy. from the bicycle		
	frame.		
1	Lock nut	1	Left-hand screw
2	Spider & Chainring(s)	1	
3	Flange bolt (M8)	3	
4	Flange nut (M8)	3	
5	Drive Unit assy.	1	
			Reverse the removal process for installation.

<PW-X> Drive Unit assy.



Order	Job/Part	Q'ty	Remarks
	Removal of the Drive Unit		Follow the work procedures for removal.
	assy. from the bicycle		
	frame.		
1	Lock nut	1	Left-hand screw
2	Spider & Chainring(s)	1	
3	Bolt (M6)	2	
4	Washer	2	
5	Bolt (M8)	2	
6	Washer	2	
7	Drive Unit assy.	1	
			Reverse the removal process for installation.





Introduction

NOTICE

Because a Drive Unit assy. is a precision machinery, do not disassemble or exert any strong force on it (for example, do NOT hit this product with a hammer).

Especially the crank axle is directly connected to the inside of the Drive Unit assy., any large damages inflicted on the crank axle may lead to failures.

Removing the Drive Unit assy.

Remove the parts in the order listed in "Removal of the Drive Unit assy. from the bicycle frame".

TIP_

To remove the Drive Unit assy. from the bicycle frame easily, loosen the bolt (M6) [6] 2–3 turns, and then lightly tap the bolt head with a plastic hammer to push in the protruding portion [a] of the Drive Unit assy. plug.

Installing the Drive Unit assy.

- 1. Install:
- Drive Unit assy. [1]
- Bolt (M8) and washer × 2 [2]
- Bolt (M6) and washer × 2 [3]

TIF

- Before installing the Drive Unit assy. to the bicycle frame, lightly tap the protruding portion
 [a] of the Drive Unit assy. plug with a plastic hammer to push it in.
- Apply LOCTITE 263 to the threaded portion of the bolt (M6) [3].
- Do not fully tighten the bolt and washer.
- 2. Tighten:
- Bolt (M8) and washer [2] × 2

22 N·m (2.2 kgf·m)

• Bolt (M6) and washer [3] × 2

11 N·m (1.1 kgf·m)

3. Install:

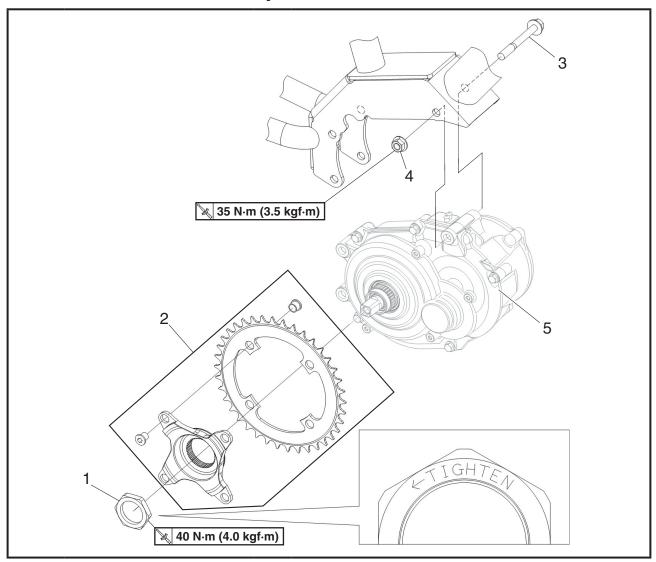
Spider & Chainring(s) [4] Lock nut (Left-hand screw) [5]

4. Tighten:

Lock nut (Left-hand screw) [5]

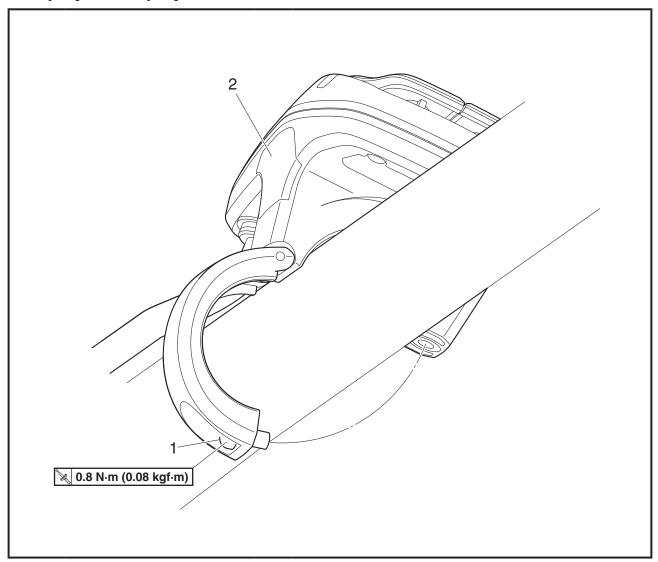
| 🥦 45 N⋅m (4.5 kgf⋅m)

<PWseries TE> Drive Unit assy.



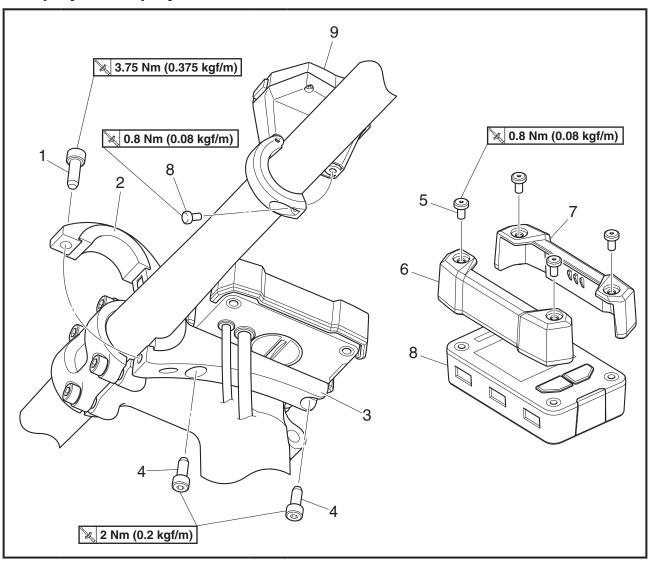
Order	Job/Part	Q'ty	Remarks
	Removal of the Drive Unit		Follow the work procedures for removal.
	assy. from the bicycle		
	frame.		
1	Lock nut	1	Left-hand screw
2	Spider & Chainring(s)	1	
3	Flange bolt (M8)	3	
4	Flange nut (M8)	3	
5	Drive Unit assy.	1	
			Reverse the removal process for installation.

<Display A> Display Unit



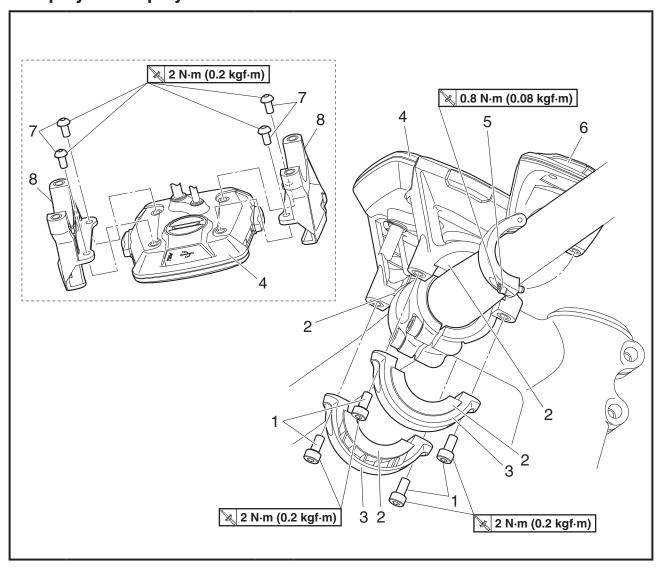
Order	Job/Part	Q'ty	Remarks
	Removal of the display		Follow the work procedures for removal.
	unit from the bicycle han-		
	dle.		
1	Bolt	1	
2	Display unit	1	
			Reverse the removal process for installation.

<Display X> Display Unit



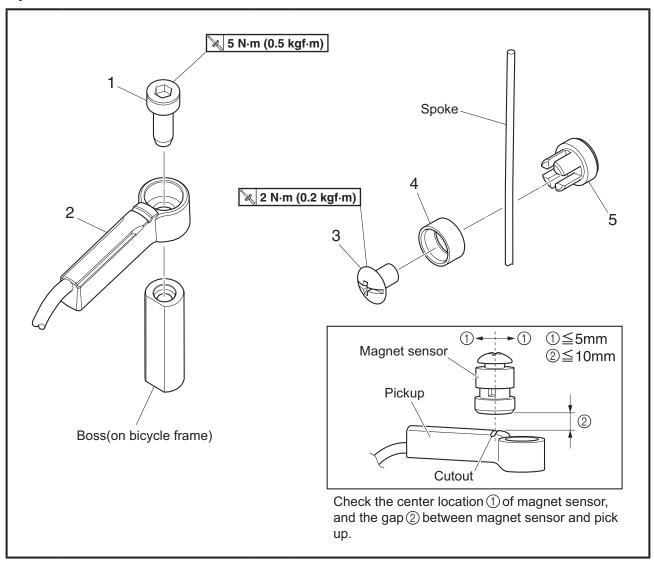
Order	Job/Part	Q'ty	Remarks
	Removal of the display and switch from the bicycle handle.		Follow the work procedures for removal.
1	Bolt	1	
2	Rubber adapter	2	
3	Clamp	1	
4	Bolt	2	
5	Bolt	4	
6	Display cover (L)	1	
7	Display cover (R)	1	
8	Display	1	
9	Screw	1	
10	Switch	1	
			Reverse the removal process for installation.

<Display C> Display Unit



Order	Job/Part	Q'ty	Remarks
	Removal of the display and switch from the bicycle handle.		Follow the work procedures for removal.
1	Bolt	4	
2	Rubber adapter	4	
3	Clamp	2	
4	Display	1	
5	Bolt	1	
6	Switch	1	
7	Bolt	4	
8	Display holder	2	
			Reverse the removal process for installation.

Speed Sensor



Order	Job/Part	Q'ty	Remarks
	Removal of the speed		Follow the work procedures for removal.
	sensor from the bicycle.		
1	Bolt	1	
2	Pickup assy.	1	
3	Bolt	1	
4	Ноор	1	
5	Magnet sensor	1	
			Reverse the removal process for installation.

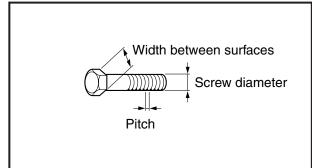
Tightening Torque

Unit: N·m kgf·m (in)

Tightening locations	Screw diameter	Q'ty	Tightening torque	Notes
(PWseries SE and PWseries TE) Drive sprocket lock nut	M27	1	40 (4.0)	Left hand screw
(PWseries SE and PWseries TE) Drive Unit fixed bolt & nut	M8	3	35 (3.5)	
(PW-X) Drive sprocket lock nut	M32	1	45 (4.5)	Left hand screw The part can be removed and installed using a commercially available bottom bracket tool.
(PW-X) Drive Unit fixed bolt	M8	2	22 (2.2)	
(PW-X) Drive Unit fixed bolt	M6	2	11 (1.1)	
(Display A) Switch fixed screw	M3	1	0.8 (0.08)	
(Display X) Clamp fixed bolt	M5	1	3.75 (0.375)	
(Display X) Display fixed bolt	M4	2	2 (0.2)	
(Display X) Display cover fixed bolt	М3	4	0.8 (0.08)	
(Display X) Switch fixed screw	МЗ	1	0.8 (0.08)	
(Display C) Clamp fixed bolt	M4	4	2 (0.2)	
(Display C) Display fixed bolt	M4	4	2 (0.2)	
(Display C) Switch fixed screw	M3	1	0.8 (0.08)	
Pickup assy.	M5	1	5 (0.5)	Because the parts are provided by the bicycle manufacturer, the tightening torque is for reference only.
Magnet sensor	_	1	2 (0.2)	

Other, general tightening torques

The tightening torques of bolts and nuts other than those with tightening force for specified locations is determined by the screw diameter (width between two surfaces) and the pitch.



Screw diameter (width between two surfaces) × pitch		
M4 (7) D0 7	1.5 to 2.5 N⋅m	
M4 (7 mm) \times P0.7	(0.15 to 0.25 kgf⋅m)	
M5 (0)	3 to 4.5 N⋅m	
M5 (8 mm) × P0.8	(0.3 to 0.45 kgf·m)	
M0 (40 mm) + D4 0	5 to 8 N⋅m	
M6 (10 mm) × P1.0	(0.5 to 0.8 kgf·m)	
M0 (40) D4 05	12 to 19 N⋅m	
M8 (12 mm) × P1.25	(1.2 to 1.9 kgf⋅m)	

System malfunction

This model is equipped with a self-diagnosis function in order to ensure that the assist system is operating normally.

If this function detects a malfunction in the system, it immediately operates the assist system under substitute characteristics and displays the error indication to alert the rider that a malfunction has occurred in the system.

For details about error codes, see the error code tables.

In addition, the Yamaha e-kit diagnostic tool can be connected to this model for more detailed trouble-shooting. For details, see "YAMAHA E-KIT DIAGNOSTIC TOOL".

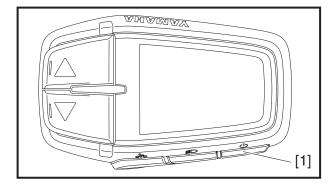
List of Error Codes Display

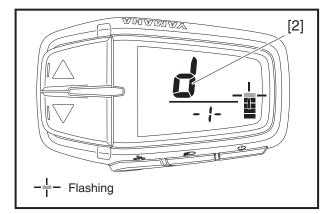
Display pattern	Error codes	Fault device	Power assist behavior and error code record
	12	Drive Unit – Display unit communication	Power assist is normal.
	13	Display unit	Error code does not record.
	31		
	32		
STD STD	33		
	34	Torque sensor	
 	35		
	36		
	37		
	38	Crank sensor	
Alternately displays	39		Power assist will stop after
	61	Controller	determine the error.
*	62	Motor	Error code will record.
	63		
	66	Controller	
	64		
STD =	67	Motor	
	68	Encoder	
	71		
	73	Battery	
	74	DO/DO	
	79	DC/DC converter	
		(Even if the wheel where the speed sensor is installed rotates, the value displayed on the speedometer section of the display unit does not change from "0".) Speed sensor	Power assist is normal. Error code does not re- cord.
The function display flashes	-	(When the wheel where the speed sensor is installed rotates, the speed is displayed on the speedometer section of the display unit.) This is not a malfunction. It is in a state that the operation of the power assist system is normal. This state may occur depending on the pedaling strength and riding speed, but it returns to normal condition if it is confirmed that the system is normal. (When charging while the battery is installed to the bicycle) This state may occur during the battery internal temperature is -20°C or less or 80°C or higher, but it returns to normal condition if battery internal temperature returns to the normal temperature range.	Power assist will stop during determine the error. Error code does not record.

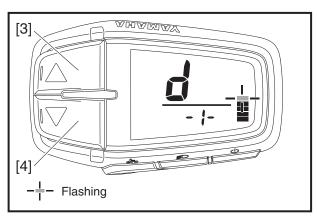
Display pattern	Error codes	Fault device	Power assist behavior and error code record
Even if the power switch is pressed to turn the power on, the power turns off automatically after 4 seconds.	-	Drive Unit - Battery	Power assist will stop after determine the error. Error code does not record.
The Automatic mode indicator flashes	-	Angle sensor To troubleshoot or check the status of malfunctions related to the angle sensor, use the Yamaha e-kit diagnostic tool that was provided separately by Yamaha. (See page 3-14.)	Power assist is normal. Error code does not record.

Self-diagnosis mode

This is the mode in which each type of diagnosis and the content of error codes, which are stored when there is an error, are displayed. You can switch between speed sensor diagnosis mode, Drive Unit diagnosis mode, error log check mode and firmware ver. check mode by the display unit operation.







Operating procedures to selfdiagnosis mode

1. Make sure that the power is turned off to the display unit.

Press the power switch [1] to turn on the power.

When the power is turned on, all segments of the display unit will come on.

After approximately 2 seconds, the segments will turn off, and then the display will return to normal.

Press the power switch [1] again, and continue pressing the switch until the "d" [2] is displayed (approximately 10 seconds).
 Confirm that the "d" [2] is displayed, and then release the power switch [1].

TIP

Steps 1 and 2 must be performed within 30 seconds.

- 3. Press the assist mode switch [3] or [4] to change the diagnosis menu.
- 4. Hold down the assist mode down switch [4] for 2 seconds to enter the selected diagnosis mode.

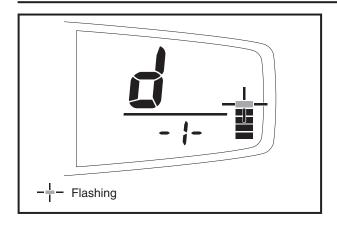
TIP.

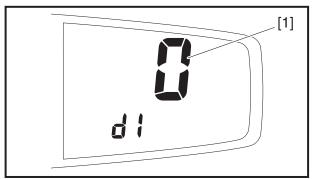
If you pressed the wrong switch, turn off the power and perform steps 1–4 again.

Self-diagnosis mode table

Layer 1	Layer 2	Layer 3	Layer 4	Description
	Speed sensor diagnosis mode	Speed sensor rotation check		Checks the functionality of the speed sensor operation
		Torque sensor reference voltage		Displays the condition of the torque sensor reference voltage
		d2-2 Motor current		Checks the functionality of the motor current (%)
	Drive Unit	d2-3 Error display		Displays the error from the motor and controller
Normal display	diagnosis mode	Display unit function check	All segments Illuminate	Checks the functionality of the display unit operation
	Error log check mode	Error log results		Retrieves the fault records from the controller to display the list of error codes
	Firmware ver.	17092 Meter hardware		Imports the display hardware version
	check mode End EXIT			EXIT

 $^{-\}frac{1}{1}$ Flashing





Speed sensor diagnosis mode display method

To determine if the controller is correctly recognizing the speed sensor signal, rotate the wheel to which the speed sensor is connected and make sure that the number of rotations of the wheel indicated matches the actual number of rotations.

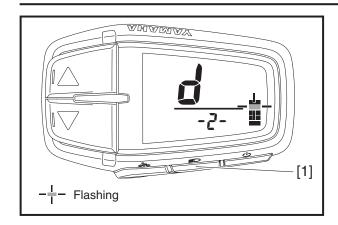
- Enter the speed sensor diagnosis mode.
 See "Operating procedures to self-diagnosis mode".
 - Confirm that the function display is displaying "d1".
- 2. When you raise and rotate the wheel (with the speed sensor), the rotation number display [1] on the display unit will change.

 Before rotating the wheel (with the speed sensor), <0> will be displayed on the rotation number display [1] of the display unit.

 Each rotation of the wheel is counted. The rotation number display shows up to <99> and will return to <0> when the wheel is rotated 100 times.

TIP_

- You should at least rotate the wheel (with the speed sensor) 3 times and make sure that <3> is displayed.
- If the speed sensor malfunctions, the number of rotations displayed on the display unit will increase before the wheel (with the speed sensor) is rotated even once, or the number will not increase even when the wheel (with the speed sensor) is rotated once (or there is a delay in the increase in the value).



Drive Unit diagnosis mode display method

You can check the status of malfunctions in the Drive Unit.

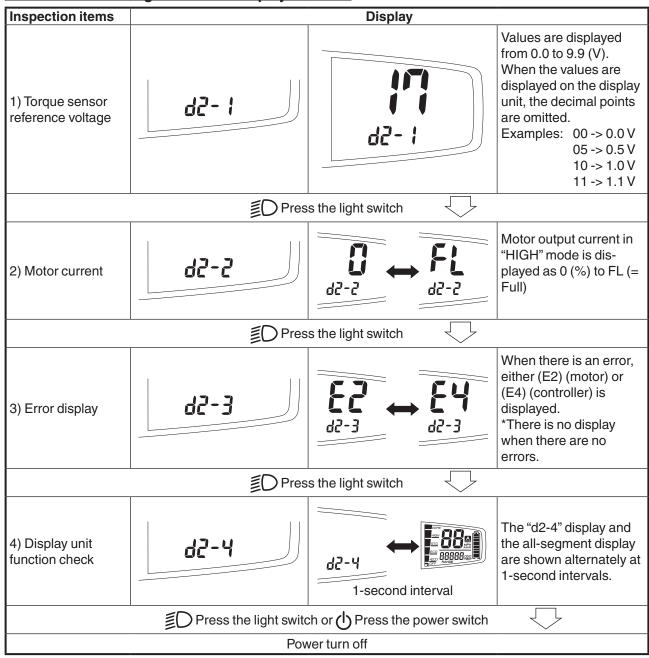
1. Enter the Drive Unit diagnosis mode.

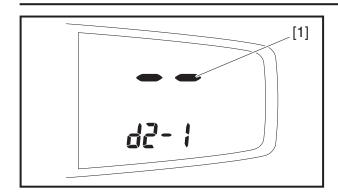
See "Operating procedures to self-diagnosis mode".

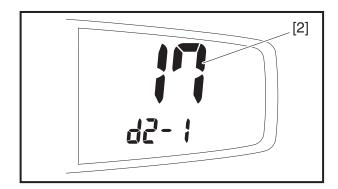
Confirm that the function display is displaying "d2-1".

Press the light switch [1] to select the torque sensor reference voltage, motor current, error displays (<E2>, <E4>), and the display unit function check.

List of Drive Unit diagnosis mode display methods







* Determining whether or not the torque sensor is good

0.2 to 1.1 V = normal

If the torque sensor is outside of this range

->Implement the torque sensor reference voltage adjustment function.

If the torque sensor remains outside of its normal range after torque sensor reference voltage adjustment

->Torque sensor malfunction (replace)

1) Torque sensor reference voltage

- 1. Torque sensor reference voltage display
- a. <- -> is displayed in the diagnosis mode display [1] of the display unit for several seconds.
- b. Values are displayed from 0.0 to 9.9 (V) in the diagnosis data display [2] of the display unit. When the values are displayed on the display unit, the decimal points are omitted.

Examples: 00 -> 0.0 V

05 -> 0.5 V

10 -> 1.0 V

11 -> 1.1 V

- c. The torque sensor is normal if the display voltage is 0.2 to 1.1 V.
 - Perform a torque sensor reference voltage adjustment if values outside of this range are displayed.
- d. Press the light switch " of the display unit.
- e. Proceed to 2) Motor current.

Torque sensor reference voltage adjustment function.

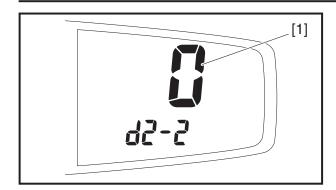
Turn the power on to the display unit and let it stand.

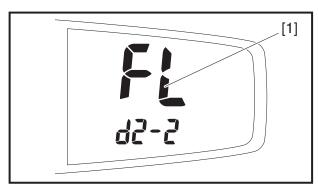
Guideline: Until the power to the display unit is turned off automatically (about

5 min.).

TIP_

Do not place feet on the pedals while performing a torque sensor reference voltage adjustment.



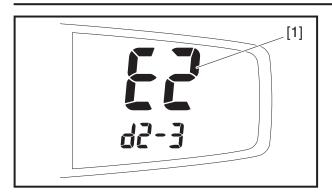


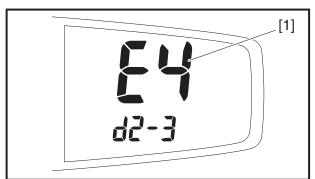
2) Motor current

- a. The diagnosis data display [1] of the display unit displays the motor output current (%).
- b. Confirm that the diagnosis data display [1] of the display unit displays <FL> when applying the rear brake and strongly pressing on the pedals.
 - <FL> is displayed: good
 - <FL> is not displayed: If the bicycle was ridden immediately before checking the motor current, it is possible that the battery or the controller temperature control is working; therefore, wait until the bicycle cools down.

If the bicycle was not ridden immediately before checking the motor current, recheck using a battery that is operating properly.

- <FL> is not displayed: The battery response is weak in winter (low temperatures), so use a battery that has been stored in a heated room.
- <FL> is not displayed: Replace the controller assembly.
- c. Press the light switch " of the display unit.
- d. Proceed to 3) Error display.





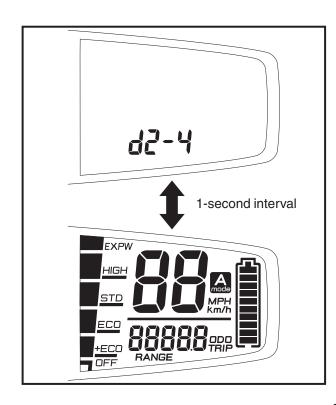
3) Error display

- a. When there is a malfunction, <E2> (motor) or <E4> (controller) will be displayed on the diagnosis data display [1] of the display unit.
- b. Press the light switch " of the display unit.
- c. Proceed to 4) Display unit function check.

TIP

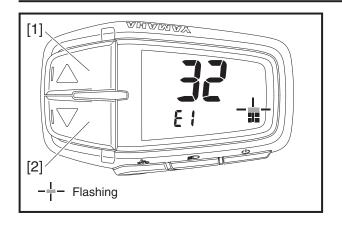
Check the error code if <E2> or <E4> is displayed.

- When there is no malfunction, the next "d2-4" is displayed without the diagnosis mode "d2-3" being displayed.
- Perform a final check to make sure there is no error display in this mode when performing repairs or replacing parts.



4) Display unit function check

- a. The "d2-4" display and the all-segment display are shown alternately at 1-second intervals.
- b. Replace the display unit if there are segments which are not illuminated.
- c. Press the power switch "(b)" of the display unit.
- d. The power to the display unit is turned off.



Error log check mode display method

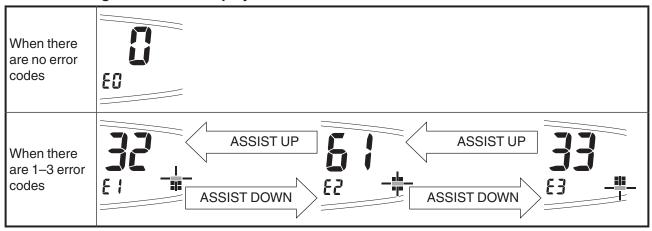
The three most recent types of error codes which are stored when there is an error are stored.

 Enter the error log check mode.
 See "Operating procedures to self-diagnosis mode".

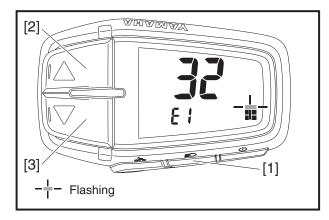
The display unit displays the three most recent error codes. To display the error codes, press the assist mode switch [1] or [2].

"E0" will be displayed when there are no errors. Press the power switch to turn off the display unit. Press the assist mode switches [1] or [2] to switch the display.

List of error log check mode display methods





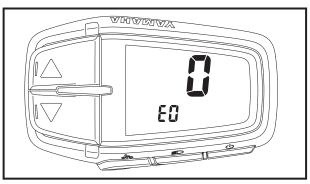


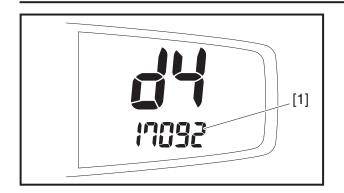
How to delete the malfunction history

- 1. While pressing the light switch [1] during the error code display, press the assist mode switches [2] or [3].
- 2. When the history is deleted, "E0" is displayed. Press the power switch to turn off the display unit.

TIP_

Be sure to clear the diagnosis history after replacing the motor or other parts.





Firmware ver. check mode

You can confirm the version information for the firmware of the meter

 Enter the firmware ver. check mode.
 See "Operating procedures to self-diagnosis mode".

Confirm that the speed meter area is displaying "d4".

The multifunction display [1] of the display unit displays the firmware version of the meter.

TIP_

Detailed version information will be provided from Yamaha separately as needed.

List of error codes and corresponding assist operation

Error codes	Fault device	Fault details	Restoration condition	Action	
12	Display unit	Stopped the communications to the display unit	If the system will not detect any errors, the system can return to normal immediately.	Check the display unit connector. Replace the display unit assembly. Replace the wire lead 2. Replace the controller assembly.	
13	Drive Unit - Display unit	Communication data failure to display unit		Make sure that the combination of Drive Unit and display unit are correct.	
		No communication signals			
		Disconnected			
31		Short-circuited	If the system will not detect any	Replace the torque sensor	
		Wiring failure between the torque sensor and the controller	errors, the system can return to normal when the power is	assembly. 2. Replace the controller	
32	Torque sensor	Wiring failure between the coil and the circuit board (wire chattering: nearly disconnect- ed)	cycled.	assembly.	
33	3611301	Abnormal no-load voltage	If the system will not detect any	Perform the torque sensor reference voltage adjustment. Replace the torque sensor assembly. Replace the controller	
34		Abnormal voltage (detected	errors, the system can return to		
35		during running / with high constant voltage)	normal when the power is cycled.		
36		Abnormal voltage (detected during running / others)	(When the system detects same error several times, the		
37		Abnormal voltage (detected during running at low speeds)	system can not return to normal even if the power is cycled.)	assembly.	
38	Crank	Torque sensor or crank sensor failure	If the system will not detect any errors, the system can return to	Replace the torque sensor assembly or controller assembly or drive axle assembly.	
39	sensor	Short-circuited or crank sensor failure	normal when the power is cycled.	Replace the controller assembly or drive axle assembly.	
61	Controller	Abnormal voltage of the sensor for U phase current while the motor is not operating	If the system will not detect any errors, the system can return to	Replace the controller assem-	
61	61 Controller	Abnormal voltage of the sensor for W phase current while the motor is not operating	normal when the power is cycled.	bly.	
		Over current is applied to the U phase of the motor			
	62 Motor	Over current is applied to the V phase of the motor		Replace the controller assembly.	
60		Over current is applied to the W phase of the motor	The system can not return to		
02		Abnormal current is applied to the U phase of the motor	normal even if the power is cycled.		
		Abnormal current is applied to the V phase of the motor			
		Abnormal current is applied to the W phase of the motor			

Error	Fault				
codes	device	Fault details	Restoration condition	Action	
63		Failure in data reading	If the system will not detect any		
66	66	External memory data error	errors, the system can return to normal when the power is	Replace the controller assembly.	
00		EEPROM error	cycled.		
	Controller	Detected circuit board temperature is too low (–20°C)	If the system will not detect any errors, the system can return to		
64		Detected circuit board tempera- ture is too high (125°C) (including DC circuit)	normal when the power is cycled. (When the system detects same error several times, the		
		Sensor on the board is nearly detached	system can not return to normal even if the power is cycled.)		
		2 lead wires are disconnected			
		Yellow lead wire is disconnected (U phase)	If the system will not detect any errors, the system can return to	Replace the controller assembly.	
67	Motor	Blue lead wire is disconnected (V phase)	normal when the power is cycled.	Replace the wire lead 3 or wire lead 4 or wire lead 5.	
		White lead wire is disconnected (W phase)			
68	Encoder	Disconnected or led wire is short-circuited	If the system will not detect any errors, the system can return to	Check the encoder connector. Replace the encoder lead wire.	
00	Encoder	Black wire is short-circuited	normal when the power is cycled.	3. Replace the controller assembly. 4. Replace the motor assembly.	
71	. Battery	Can't receive data from battery correctly	If the system will not detect any errors, the system can return to	Replace the plug D.C. receptacle or wire lead 2. Replace the controller assembly. Replace the battery assembly.	
73	- Laurency	Detected battery voltage is too high (45V)	normal when the power is cycled.	Replace the controller assembly. Replace the battery assembly.	
74		Internal system failure		Replace the battery assembly.	
79	DC/DC converter	Abnormal DC current	If the system will not detect any errors, the system can return to normal when the power is cycled.	Replace the external DCDC converter. Replace the controller assembly.	
_	Speed sensor	Speed sensor disconnected	If the system will not detect any errors, the system can return to normal immediately.	Check the speed sensor lead connector. Check the gap between the pick up and the magnet sensor. Replace the speed sensor set.	
-	Drive Unit - Battery	Communication error between the Drive Unit and the battery	If the system will not detect any errors, the system can return to normal immediately.	Check the battery communication connector. Replace the plug DC. Replace the controller assembly. Replace the battery.	

YAMAHA E-KIT DIAGNOSTIC TOOL

This model uses the Yamaha e-kit diagnostic tool to identify malfunctions.

For more information about using the Yamaha e-kit diagnostic tool, refer to the operation manual that is included with the tool.

Functions of the Yamaha e-kit diagnostic tool

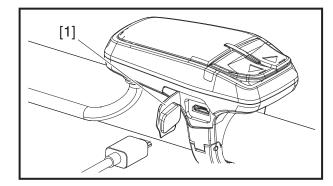
Drive Unit malfunction diagnosis:

Drive Unit malfunction codes recorded on the controller are read, and the contents are displayed. The freeze frame data (FFD) is the operation data when a malfunction was detected. This data can be used to identify when the malfunction occurred and check the Drive Unit conditions and running conditions when it occurred.

Drive Unit system function test: Check the operation and the output value of each sensor

and actuator.

Battery information: Displays the battery data.



Connecting the Yamaha e-kit diagnostic tool

- Open the USB receptacle cap [1] of the display.
- 2. Connect the USB cable to the switch and computer with the Yamaha e-kit diagnostic tool.

TIP.

- After disconnecting the USB cable, be sure to close the USB receptacle cap [1].
- For the USB cable, use a Type-A to Micro-B cable that is not an OTG cable.
- When the Yamaha e-kit diagnostic tool is connected to the vehicle, the operation of the multifunction meter and indicators will be different from the normal operation.

System malfunction

This model is equipped with a self-diagnosis function in order to ensure that the assist system is operating normally.

If this function detects a malfunction in the system, it immediately operates the assist system under substitute characteristics and displays the error indication to alert the rider that a malfunction has occurred in the system.

For details about error codes, see the error code tables.

In addition, the Yamaha e-kit diagnostic tool can be connected to this model for more detailed trouble-shooting. For details, see "YAMAHA E-KIT DIAGNOSTIC TOOL".

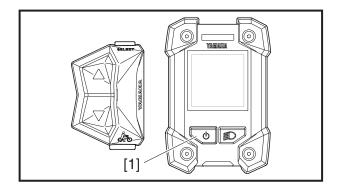
List of Error Codes Display

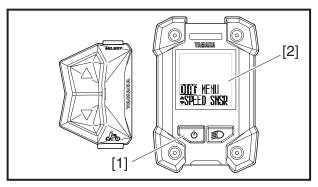
Display pattern	Error codes [1]	Error message [2]	Fault device	Power assist behavior and error code record
LED indicator: RED	12	METER CHK CONN	Drive Unit – Display unit communication	Power assist is normal.
	13	DU-METER INCOMPATIBLE	Display unit	Error code does not record.
	31			
YAMAHA	32	TRQ SNSR		
* *************************************	33			
	34	PWR OFF/ON	Torque sensor	
[41] A A A A A A A A A A A A A A A A A A A	35			
[1] — <u>31)</u> TRQ SNSR	36 37			
	38	001/01/00		
	39	CRK SNSR PWR OFF/ON	Crank sensor	
Alternately	61	CONT	Controller	
displays	62	PWR OFF/ON MOTOR	Motor	Power assist will stop after
LED indicator: RED	63	PWR OFF/ON	Controller	determine the error. Error code will record.
LED Indicator. NED	66	CONT		
	64	PWR OFF/ON		
YAMAHA O	67	MOTOR PWR OFF/ON	Motor	
***************************************	68	ENCODER PWR OFF/ON	Encoder	
	71	71 BATTERY PWR OFF/ON	Battery	
31 TOO GNOD	73			
31)TRQ SNSR PWR OFF/ON	74			
PAR OIT/OIT	79	DC/DC PWR OFF/ON	DC/DC converter	
SPD SNSR CHK MAGNET	-	SPD SNSR CHK MAGNET	Speed sensor	Power assist is normal. Error code does not record.
Even if the power switch is pressed to turn the power on, the power turns off automatically after 4 seconds.	_	-	Drive Unit - Battery	Power assist will stop after determine the error. Error code does not record.

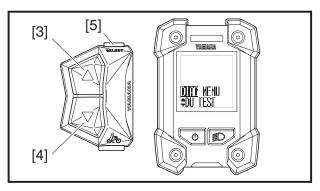
Display pattern	Error codes [1]	Error message [2]	Fault device	Power assist behavior and error code record
"A:###" and "###" on the assist mode indicator are alternately displayed. A:SID AVE 20.0 km/h AUE 20.0 km/h * In the case of Standard mode	_	_	Angle sensor To troubleshoot or check the status of malfunctions related to the angle sensor, use the Yamaha e-kit diagnostic tool that was provided separately by Yamaha. (See page 4-14.)	Power assist is normal. Error code does not record.
The assist mode indicator and function display are flashing. STD AWE 20.0 km/h	_	_	This is not a malfunction. It is in a state that the operation of the power assist system is normal. This state may occur depending on the pedaling strength and riding speed, or it may occur during the battery internal temperature is -20°C or less or 80°C or higher, but it returns to normal condition if it is confirmed that the system is normal, or battery internal temperature returns to the normal temperature range. (When the wheel where the speed sensor is installed rotates, the speed is displayed on the speedometer section of the display unit.) This is not a malfunction. It is in a state that the operation of the power assist system is normal. This state may occur depending on the pedaling strength and riding speed, but it returns to normal condition if it is confirmed that the system is normal. (When charging while the battery is installed to the bicycle) This state may occur during the battery internal temperature is -20°C or less or 80°C or higher, but it returns to normal condition if battery internal temperature returns to the normal temperature range.	Power assist will stop during determine the error. Error code does not record.

Self-diagnosis mode

This is the mode in which each type of diagnosis and the content of error codes, which are stored when there is an error, are displayed. You can switch between speed sensor diagnosis mode, Drive Unit diagnosis mode, and error log check mode by the display unit operation.







Operating procedures to selfdiagnosis mode

1. Make sure that the power is turned off to the display unit.

Press the power switch [1] to turn on the power.

When the power is turned on, the initial display sequence is shown, and then the display will return to normal.

Press the power switch [1] again, and continue pressing the switch until the DIAG MENU [2] is displayed (approximately 10 seconds).
 Confirm that the DIAG MENU is displayed, and then release the power switch [1].

TIP

Steps 1 and 2 must be performed within 30 seconds.

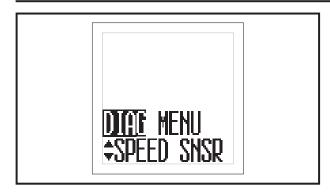
- 3. Press the assist mode switch [3] or [4] to change the DIAG MENU.
- 4. Press the function select switch [5] to enter the selected self-diagnosis mode.

TIP

If you pressed the wrong switch, turn off the power and perform steps 1–4 again.

Self-diagnosis mode table

Layer 1	Layer 2	Layer 3	Layer 4	Description
	Speed sensor diagnosis mode	Speed sensor rotation check		Checks the functionality of the speed sensor operation
	diagnosis mode	Torque sensor reference voltage		Displays the condition of the torque sensor reference voltage
	HITTE MENII	DIGIT % DU CURRENT Motor current		Checks the functionality of the motor current (%)
	DIAE MENU DIVENT Drive Unit diagnosis mode	DIATE ERR DU RESULT Error display		Displays the error from the motor and controller
+ECO ODO 157 km Normal display		DISPLAY Display unit function check	All segments Illuminate	Checks the functionality of the display unit operation
	DIME MENU SERROR INFO	NO ERROR Error log results		Retrieves the fault records from the controller to display the list of error codes
	Firmware ver.	DRT+HARD. M ***-**-*** Meter hardware		Imports the display hardware version
		DMF\$S0FT. M ********** Meter software		Imports the display firmware version
		######################################		Imports the Drive Unit hardware version
		DAT \$SOFT. DU ************ Drive Unit software		Imports the Drive Unit firmware ver- sion
	DIAG MENU			EXIT





Speed sensor diagnosis mode display method

To determine if the controller is correctly recognizing the speed sensor signal, rotate the wheel to which the speed sensor is connected and make sure that the number of rotations of the wheel indicated matches the actual number of rotations.

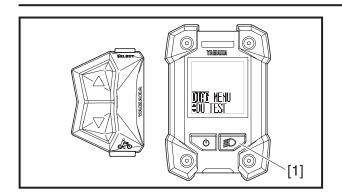
- Enter the speed sensor diagnosis mode.
 See "Operating procedures to self-diagnosis mode".
- 2. When you raise and rotate the wheel (with the speed sensor), the rotation number display [1] on the display unit will change.

 Before rotating the wheel (with the speed sensor), <0> will be displayed on the rotation number display [1] of the display unit.

 Each rotation of the wheel is counted. The rotation number display shows up to <999> and will return to <1> when the wheel is rotated 1,000 times.

TIP_

- You should at least rotate the wheel (with the speed sensor) 3 times and make sure that <3> is displayed.
- If the speed sensor malfunctions, the number of rotations displayed on the display unit will increase before the wheel (with the speed sensor) is rotated even once, or the number will not increase even when the wheel (with the speed sensor) is rotated once (or there is a delay in the increase in the value).



Drive Unit diagnosis mode display method

You can check the status of malfunctions in the Drive Unit.

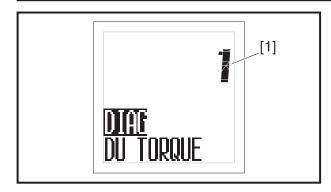
Enter the Drive Unit diagnosis mode.
 See "Operating procedures to self-diagnosis

mode".

Press the light switch [1] to select the torque sensor reference voltage, motor current, error displays (<E2>, <E4>), and the display unit function check.

List of Drive Unit diagnosis mode display methods

Inspection items	Display				
1) Torque sensor reference voltage	DIAF (V) DU TORQUE	DIAF (V) DU TORQUE	Values are displayed from 0.0 to 5.0 (V)		
	Press	the light switch			
2) Motor current	DIAF % DU CURRENT	DICE % DU CURRENT	Motor output current in "HIGH" mode is displayed as 0 to 100 (= % output)		
	Press the light switch				
3) Error display	DIAT ERR DU RESULT	F2 DIGT ERR DU RESULT . DU RESULT	When there is an error, either (E2) (motor) or (E4) (controller) is displayed. *There is no display when there are no errors.		
Press the light switch					
4) Display unit function check	DIAF DISPLAY	**************************************	All segments are illuminated. (Segments that are not illuminated indicate a malfunction.)		
Press the light switch or Press the power switch					
Power turn off					





* Determining whether or not the torque sensor is good

0.2 to 1.1 V = normal

If the torque sensor is outside of this range

->Implement the torque sensor reference voltage adjustment function.

If the torque sensor remains outside of its normal range after torque sensor reference voltage adjustment

->Torque sensor malfunction (replace)

1) Torque sensor reference voltage

- 1. Torque sensor reference voltage display
- a. <1> is displayed in the diagnosis mode display [1] of the display unit for several seconds.
- b. Displayed in units of 0.1 V in the diagnosis data display [2] of the display unit.
- c. The torque sensor is normal if the display voltage is 0.2 to 1.1 V.
 Perform a torque sensor reference voltage adjustment if values outside of this range are displayed.
- d. Press the light switch " of the display unit.
- e. Proceed to 2) Motor current.

<u>Torque sensor reference voltage</u> <u>adjustment function.</u>

Turn the power on to the display unit and let it stand.

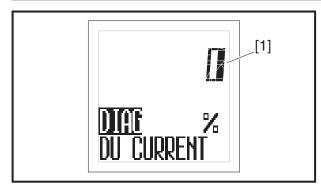
Guideline: Until the power to the display unit

is turned off automatically (about

5 min.).

TIP_

Do not place feet on the pedals while performing a torque sensor reference voltage adjustment.



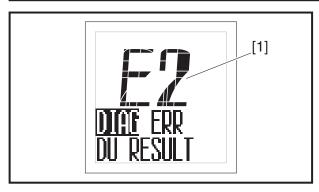


2) Motor current

- a. The diagnosis data display [1] of the display unit displays the motor output current (%).
- b. Confirm that the diagnosis data display [1] of the display unit displays <100> when applying the rear brake and strongly pressing on the pedals.
 - <100> is displayed: good
 - <100> is not displayed: If the bicycle was ridden immediately before checking the motor current, it is possible that the battery or the controller temperature control is working; therefore, wait until the bicycle cools down.

If the bicycle was not ridden immediately before checking the motor current, recheck using a battery that is operating properly.

- <100> is not displayed: The battery response is weak in winter (low temperatures), so use a battery that has been stored in a heated room.
- <100> is not displayed: Replace the controller assembly.
- c. Press the light switch "of the display unit.
- d. Proceed to 3) Error display.





3) Error display

a. When there is a malfunction, <E2> (motor) or
 <E4> (controller) will be displayed on the diagnosis data display [1] of the display unit.

TIP

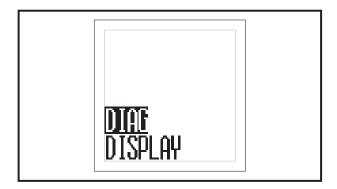
Check the error code if <E2> or <E4> is displayed.

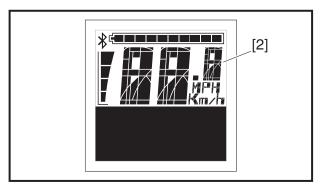
- b. Press the light switch "of the display unit."
- c. Proceed to 4) Display unit function check.

TIP

Check the error code if <E2> or <E4> is displayed.

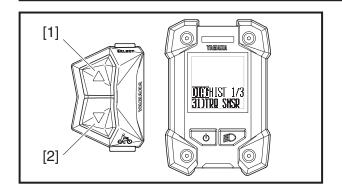
- When there is no malfunction, the next [DISPLAY] is displayed without the diagnosis mode [ERR] being displayed.
- Perform a final check to make sure there is no error display in this mode when performing repairs or replacing parts.





4) Display unit function check

- a. Press the function select switch "SELECT" 2 of the display unit.
- b. All segments of the display unit [2] will illuminate.
- c. Replace the display unit if there are segments which are not illuminated.
- d. Press the power switch " of the display unit.
- e. The power to the display unit is turned off.



Error log check mode display method

The three most recent types of error codes which are stored when there is an error are stored.

1. Enter the error log check mode.

See "Operating procedures to self-diagnosis mode".

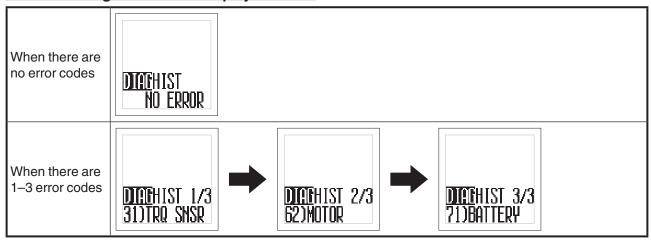
The display unit displays the three most recent error codes. To display the error codes, press the assist mode switch [1] or [2].

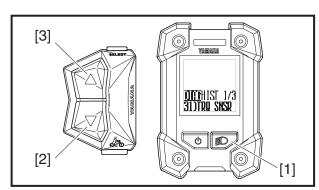
"NO ERROR" will be displayed when there are no errors.

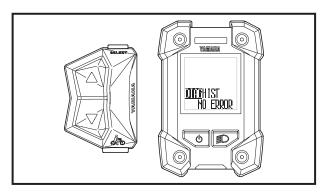
Press the power switch to turn off the display unit.

Press the assist mode switches [1] or [2] to switch the display.

List of error log check mode display methods





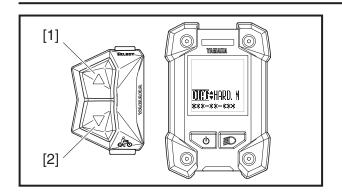


How to delete the malfunction history

- 1. While pressing the light switch [1] during the error code display, press the assist mode switches [2] or [3].
- 2. When the history is deleted, "NO ERROR" is displayed. Press the power switch to turn off the display unit.

TIP

Be sure to clear the diagnosis history after replacing the motor or other parts.



Firmware ver. check mode

You can confirm the version information for the hardware and firmware of the Drive Unit and meter.

- Enter the firmware ver. check mode.
 See "Operating procedures to self-diagnosis mode".
- 2. Press the assist mode switch [1] or [2] to display the version information for the meter hardware, meter firmware, Drive Unit hardware, and Drive Unit firmware.

TIP_

Detailed version information will be provided from Yamaha separately as needed.

List of firmware ver. check mode display methods

Items	Display
1) Meter hardware version	DICE+HARD. M ***-**
2) Meter firmware version	DIGE \$SOFT. M ******
3) Drive Unit hardware version	DIAF\$HARD. DU *****
4) Drive Unit firmware version	<u>DIAC</u> \$SOFT. DU ********

List of error codes and corresponding assist operation

Error codes	Fault device	Fault details	Restoration condition	Action	
12	Display unit	Stopped the communications to the display unit	If the system will not detect any	Check the display unit connector. Replace the display unit assembly. Replace the wire lead 2. Replace the controller assembly.	
13	Drive Unit - Display unit	Communication data failure to display unit		Make sure that the combination of Drive Unit and display unit are correct.	
		No communication signals			
		Disconnected			
31		Short-circuited	If the system will not detect any	Replace the torque sensor	
		Wiring failure between the torque sensor and the controller	errors, the system can return to normal when the power is	assembly. 2. Replace the controller	
32	Torque sensor	Wiring failure between the coil and the circuit board (wire chattering: nearly disconnect- ed)	cycled.	assembly.	
33	3611301	Abnormal no-load voltage	If the system will not detect any		
34		Abnormal voltage (detected	errors, the system can return to	Perform the torque sensor reference voltage adjust	
35		during running / with high constant voltage)	normal when the power is cycled. (When the system detects same error several times, the	reference voltage adjust- ment. 2. Replace the torque sensor assembly. 3. Replace the controller assembly.	
36		Abnormal voltage (detected during running / others)			
37		Abnormal voltage (detected during running at low speeds)	system can not return to normal even if the power is cycled.)		
38	Crank	Torque sensor or crank sensor failure	If the system will not detect any errors, the system can return to	Replace the torque sensor assembly or controller assembly or drive axle assembly.	
39	sensor	Short-circuited or crank sensor failure	normal when the power is cycled.	Replace the controller assembly or drive axle assembly.	
61	Controller	Abnormal voltage of the sensor for U phase current while the motor is not operating	If the system will not detect any errors, the system can return to	Replace the controller assem-	
61	Controller	Abnormal voltage of the sensor for W phase current while the motor is not operating	normal when the power is cycled.	bly.	
		Over current is applied to the U phase of the motor			
		Over current is applied to the V phase of the motor			
	Motor	Over current is applied to the W phase of the motor	The system can not return to	Replace the controller assembly.	
62	IVIOLOI	Abnormal current is applied to the U phase of the motor	normal even if the power is cycled.		
		Abnormal current is applied to the V phase of the motor			
		Abnormal current is applied to the W phase of the motor			

Error	Fault			
codes	device	Fault details	Restoration condition	Action
63		Failure in data reading	If the system will not detect any	
66		External memory data error	errors, the system can return to normal when the power is	
66		EEPROM error	cycled.	
64	Controller ture	Detected circuit board temperature is too low (–20°C) Detected circuit board temperature is too high (125°C)		Replace the controller assembly.
04		(including DC circuit)	(When the system detects same error several times, the	
		Sensor on the board is nearly detached	system can not return to normal even if the power is cycled.)	
		2 lead wires are disconnected		
		Yellow lead wire is disconnected (U phase)	If the system will not detect any errors, the system can return to	Replace the controller assembly.
67	Motor	Blue lead wire is disconnected (V phase)	normal when the power is cycled.	Replace the wire lead 3 or wire lead 4 or wire lead 5.
		White lead wire is disconnected (W phase)		
68	Encoder	Disconnected or led wire is short-circuited	If the system will not detect any errors, the system can return to normal when the power is cycled.	Check the encoder connector. Replace the encoder lead wire.
00	Encodei	Black wire is short-circuited		3. Replace the controller assembly. 4. Replace the motor assembly.
71	Battery	Can't receive data from battery correctly	If the system will not detect any errors, the system can return to	Replace the plug D.C. receptacle or wire lead 2. Replace the controller assembly. Replace the battery assembly.
73	,	Detected battery voltage is too high (45V)	normal when the power is cycled.	Replace the controller assembly. Replace the battery assembly.
74		Internal system failure		Replace the battery assembly.
79	DC/DC converter	Abnormal DC current	If the system will not detect any errors, the system can return to normal when the power is cycled.	Replace the external DCDC converter. Replace the controller assembly.
-	Speed sensor	Speed sensor disconnected	If the system will not detect any errors, the system can return to normal immediately.	 Check the speed sensor lead connector. Check the gap between the pick up and the magnet sensor. Replace the speed sensor set.
-	Drive Unit - Battery	Communication error between the Drive Unit and the battery	If the system will not detect any errors, the system can return to normal immediately.	Check the battery communication connector. Replace the plug DC. Replace the controller assembly. Replace the battery.

YAMAHA E-KIT DIAGNOSTIC TOOL

This model uses the Yamaha e-kit diagnostic tool to identify malfunctions.

For more information about using the Yamaha e-kit diagnostic tool, refer to the operation manual that is included with the tool.

Functions of the Yamaha e-kit diagnostic tool

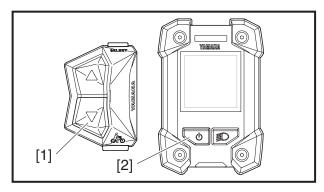
Drive Unit malfunction diagnosis:

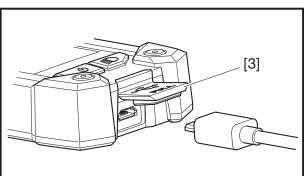
Drive Unit malfunction codes recorded on the controller are read, and the contents are displayed. The freeze frame data (FFD) is the operation data when a malfunction was detected. This data can be used to identify when the malfunction occurred and check the Drive Unit conditions and running conditions when it occurred.

Drive Unit system function test: Check the operation and the output value of each sensor

and actuator.

Battery information: Displays the battery data.





Connecting the Yamaha e-kit diagnostic tool

- Make sure that the power is turned off to the display unit.
- 2. Continue to press the assist mode switch (down) [1] and power switch [2] over 2 sec.
- 3. Confirm that the "Pc" is displayed, and then release the assist mode switch (down) [1] and power switch [2].
- 4. Open the USB receptacle cap [3] of the display.
- 5. Connect the USB cable to the switch and computer with the Yamaha e-kit diagnostic tool.

TIP

- After disconnecting the USB cable, be sure to close the USB receptacle cap [3].
- For the USB cable, use a Type-A to Micro-B cable that is not an OTG cable.
- When the Yamaha e-kit diagnostic tool is connected to the vehicle, the operation of the multifunction meter and indicators will be different from the normal operation.

System malfunction

This model is equipped with a self-diagnosis function in order to ensure that the assist system is operating normally.

If this function detects a malfunction in the system, it immediately operates the assist system under substitute characteristics and displays the error indication to alert the rider that a malfunction has occurred in the system.

For details about error codes, see the error code tables.

In addition, the Yamaha e-kit diagnostic tool can be connected to this model for more detailed trouble-shooting. For details, see "YAMAHA E-KIT DIAGNOSTIC TOOL".

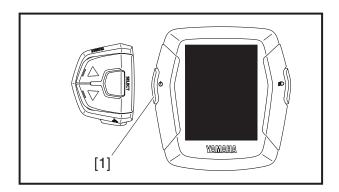
List of Error Codes Display

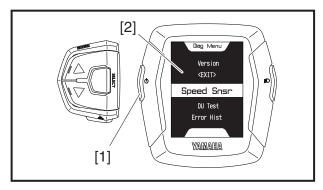
Display pattern	Error codes [1]	Error message [2]	Fault device	Power assist behavior and error code record
	12	METER CHK CONN	Drive Unit – Display unit communication	Power assist is normal.
	13	DU-METER INCOMPATIBLE	Display unit	Error code does not record.
	31			
	32			
	33	TRQ SNSR		
	34	PWR OFF/ON	Torque sensor	
	35 36	_		
	37			
ER	38	ODIC ONIOD		
	39	CRK SNSR PWR OFF/ON	Crank sensor	
	39	CONT		
[1]— <u>31)</u> TRO SNSR [2]——PWR OFF/ON	61	PWR OFF/ON	Controller	Device a solid will also after
[2]——PWR OFF/ON	62	MOTOR PWR OFF/ON	Motor	Power assist will stop after determine the error. Error code will record.
	63	CONT	Controller	Thoi code will record.
	66	PWR OFF/ON		
	64			
	67	MOTOR PWR OFF/ON	Motor	
	68	ENCODER PWR OFF/ON	Encoder	
	71 73	BATTERY PWR OFF/ON	Battery	
	74			
	79	DC/DC PWR OFF/ON	DC/DC converter	
STD.Okm/h23 STD.STD.	_	SPD SNSR CHK MAGNET	Speed sensor	Power assist is normal. Error code does not record.
Even if the power switch is pressed to turn the power on, the power turns off automatically after 4 seconds.	_	_	Drive Unit - Battery	Power assist will stop after determine the error. Error code does not record.

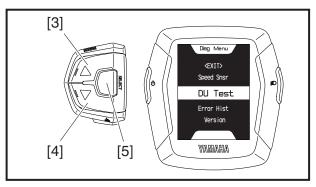
Display pattern	Error codes [1]	Error message [2]	Fault device	Power assist behavior and error code record
The Automatic Support mode indicator is flashing.				
Amade 43 STD STD 54 ODO 157 km TRIP DIST 33.1 km *)) - - Flashing	_	-	Angle sensor To troubleshoot or check the status of malfunctions related to the angle sensor, use the Yamaha e-kit diagnostic tool that was provided separately by Yamaha. (See page 5-14.)	Because the inclination cannot be detected when the bicycle is stopped while the automatic mode is selected, the bicycle will start in the "STD" mode.
The function display is flashing. Amode 13 Okm/h 30 STD 157 km THIP DIST 33. 1 km THIP DIST 33. 1 km	_		This is not a malfunction. It is in a state that the operation of the power assist system is normal. This state may occur depending on the pedaling strength and riding speed, or it may occur during the battery internal temperature is -20°C or less or 80°C or higher, but it returns to normal condition if it is confirmed that the system is normal, or battery internal temperature returns to the normal temperature range. (When the wheel where the speed sensor is installed rotates, the speed is displayed on the speedometer section of the display unit.) This is not a malfunction. It is in a state that the operation of the power assist system is normal. This state may occur depending on the pedaling strength and riding speed, but it returns to normal condition if it is confirmed that the system is normal. (When charging while the battery is installed to the bicycle) This state may occur during the battery internal temperature is -20°C or less or 80°C or higher, but it returns to normal condition if battery internal temperature returns to the normal condition if battery internal temperature returns to the normal condition if battery internal temperature returns to the normal temperature returns to the normal temperature range.	Power assist will stop during determine the error. Error code does not record.

Self-diagnosis mode

This is the mode in which each type of diagnosis and the content of error codes, which are stored when there is an error, are displayed. You can switch between speed sensor diagnosis mode, Drive Unit diagnosis mode, and error log check mode by the display unit operation.







Operating procedures to selfdiagnosis mode

1. Make sure that the power is turned off to the display unit.

Press the power switch [1] to turn on the power.

When the power is turned on, the initial display sequence is shown, and then the display will return to normal.

Press the power switch [1] again, and continue pressing the switch until the DIAG MENU [2] is displayed (approximately 10 seconds).
 Confirm that the DIAG MENU is displayed, and then release the power switch [1].

TIP

Steps 1 and 2 must be performed within 30 seconds.

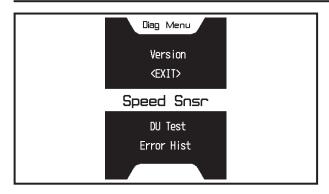
- 3. Press the assist mode switch [3] or [4] to change the DIAG MENU.
- 4. Press the function select switch [5] to enter the selected self-diagnosis mode.

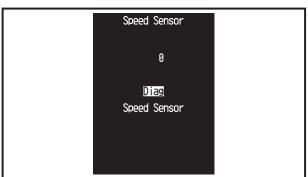
TIP

If you pressed the wrong switch, turn off the power and perform steps 1–4 again.

Self-diagnosis mode table

Layer 1	Layer 2	Layer 3	Layer 4	Description
	Version <exii> Speed Snsr Speed sensor diagnosis mode</exii>	Speed Sensor Speed sensor rotation check		Checks the functionality of the speed sensor operation
	J	Diag DU Torque Torque sensor reference voltage		Displays the condition of the torque sensor reference voltage
	Diag Menu <exit> Speed Snsr</exit>	Diag DU Current Motor current		Checks the functionality of the motor current (%)
	DU Test Drive Unit diagnosis mode	Diag Err DU Result Error display		Displays the error from the motor and controller
Amode 13 O O km/h 30		Display Display unit function check	All segments Illuminate	Checks the functionality of the display unit operation
157 km 157 km 33.1 km Normal display	Speed Snsr DIST 1.1 km *>0 Speed Snsr DU Test Error Hist	Diag Hist NO ERROR Error log results		Retrieves the fault records from the controller to display the list of error codes
		Diag Hard.M *********** Meter hardware		Imports the display hardware version
	Diag Menu DU Test Error Hist	Diag Soft. M ####### Meter software		Imports the display firmware version
	Version Firmware ver. check mode	Diag Hard, DU *********** Drive Unit hardware		Imports the Drive Unit hardware version
		Diag Soft.DU *********** Drive Unit software		Imports the Drive Unit firmware version
	Diag Menu Error Hist Version <exit> EXIT</exit>			EXIT





Speed sensor diagnosis mode display method

To determine if the controller is correctly recognizing the speed sensor signal, rotate the wheel to which the speed sensor is connected and make sure that the number of rotations of the wheel indicated matches the actual number of rotations.

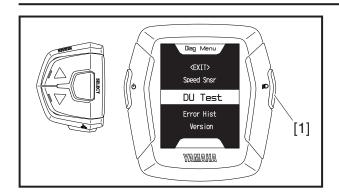
- Enter the speed sensor diagnosis mode.
 See "Operating procedures to self-diagnosis mode".
- 2. When you raise and rotate the wheel (with the speed sensor), the rotation number display [1] on the display unit will change.

 Before rotating the wheel (with the speed sensor), <0> will be displayed on the rotation number display [1] of the display unit.

 Each rotation of the wheel is counted. The rotation number display shows up to <999> and will return to <1> when the wheel is rotated 1,000 times.

TIP_

- You should at least rotate the wheel (with the speed sensor) 3 times and make sure that <3> is displayed.
- If the speed sensor malfunctions, the number of rotations displayed on the display unit will increase before the wheel (with the speed sensor) is rotated even once, or the number will not increase even when the wheel (with the speed sensor) is rotated once (or there is a delay in the increase in the value).



Drive Unit diagnosis mode display method

You can check the status of malfunctions in the Drive Unit.

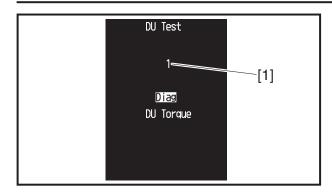
1. Enter the Drive Unit diagnosis mode.

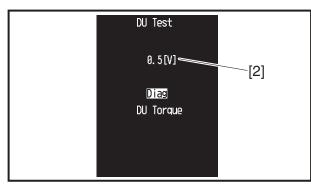
See "Operating procedures to self-diagnosis mode".

Press the light switch [1] to select the torque sensor reference voltage, motor current, error displays (<E2>, <E4>), and the display unit function check.

List of Drive Unit diagnosis mode display methods

Inspection items	spection items Display					
1) Torque sensor reference voltage	DU Test 0.5[V] DIES DU Torque DU Torque	Values are displayed from 0.0 to 5.0 (V)				
	Press the light switch	7				
2) Motor current	DU Test DU Test 10% 100% Motor output current in					
	Press the light switch	7				
3) Error display	DU Test DU Test E2 E4 DIEG Err DIEG Err DU Result DU Result DU Result	When there is an error, either (E2) (motor) or (E4) (controller) is displayed. *There is no display when there are no errors.				
	Press the light switch	7				
4) Display unit function check Disclay Disclay Disclay All segments are illuminated. (Segments that are not illuminated indicate a malfunction.)						
	Press the light switch or Press the power switch					
	Power turn off					





* Determining whether or not the torque sensor is good

0.2 to 1.1 V = normal

If the torque sensor is outside of this range

->Implement the torque sensor reference voltage adjustment function.

If the torque sensor remains outside of its normal range after torque sensor reference voltage adjustment

->Torque sensor malfunction (replace)

1) Torque sensor reference voltage

- 1. Torque sensor reference voltage display
- a. <1> is displayed in the diagnosis mode display [1] of the display unit for several seconds.
- b. Displayed in units of 0.1 V in the diagnosis data display [2] of the display unit.
- c. The torque sensor is normal if the display voltage is 0.2 to 1.1 V.
 Perform a torque sensor reference voltage adjustment if values outside of this range are displayed.
- d. Press the light switch " of the display unit.
- e. Proceed to 2) Motor current.

<u>Torque sensor reference voltage adjustment function.</u>

Turn the power on to the display unit and let it stand.

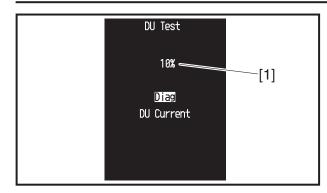
Guideline: Until the power to the display unit

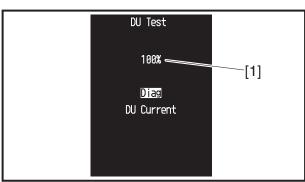
is turned off automatically (about

5 min.).

TIP_

Do not place feet on the pedals while performing a torque sensor reference voltage adjustment.



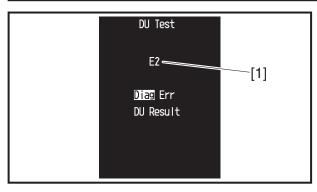


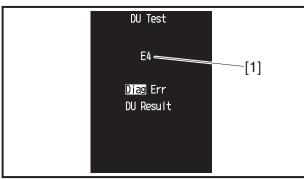
2) Motor current

- a. The diagnosis data display [1] of the display unit displays the motor output current (%).
- b. Confirm that the diagnosis data display [1] of the display unit displays <100> when applying the rear brake and strongly pressing on the pedals.
 - <100> is displayed: good
 - <100> is not displayed: If the bicycle was ridden immediately before checking the motor current, it is possible that the battery or the controller temperature control is working; therefore, wait until the bicycle cools down.

If the bicycle was not ridden immediately before checking the motor current, recheck using a battery that is operating properly.

- <100> is not displayed: The battery response is weak in winter (low temperatures), so use a battery that has been stored in a heated room.
- <100> is not displayed: Replace the controller assembly.
- c. Press the light switch " of the display unit.
- d. Proceed to 3) Error display.





3) Error display

a. When there is a malfunction, <E2> (motor) or <E4> (controller) will be displayed on the diagnosis data display [1] of the display unit.

TIP

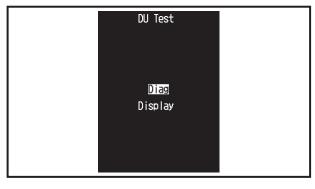
Check the error code if <E2> or <E4> is displayed.

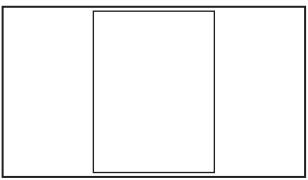
- b. Press the light switch " of the display unit.
- c. Proceed to 4) Display unit function check.

TIP

Check the error code if <E2> or <E4> is displayed.

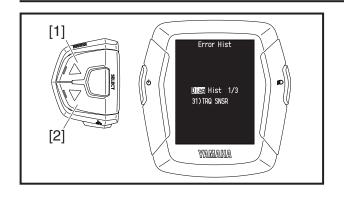
- When there is no malfunction, the next [DISPLAY] is displayed without the diagnosis mode [ERR] being displayed.
- Perform a final check to make sure there is no error display in this mode when performing repairs or replacing parts.





4) Display unit function check

- a. Press the function select switch "SELECT" 2 of the display unit.
- b. All segments of the display unit [2] will illuminate.
- c. Replace the display unit if there are segments which are not illuminated.
- d. Press the power switch "(1)" of the display
- e. The power to the display unit is turned off.



Error log check mode display method

The three most recent types of error codes which are stored when there is an error are stored.

1. Enter the error log check mode.

See "Operating procedures to self-diagnosis mode".

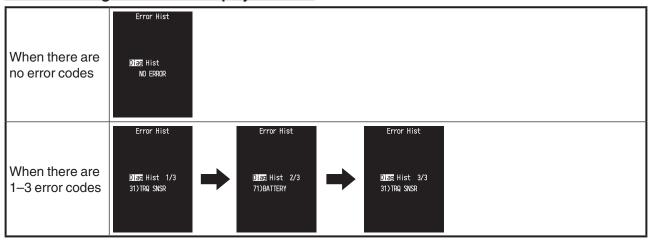
The display unit displays the three most recent error codes. To display the error codes, press the assist mode switch [1] or [2].

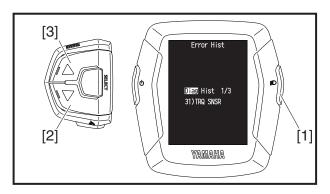
"NO ERROR" will be displayed when there are no errors.

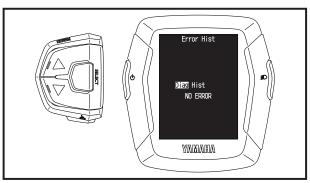
Press the power switch to turn off the display unit.

Press the assist mode switches [1] or [2] to switch the display.

List of error log check mode display methods





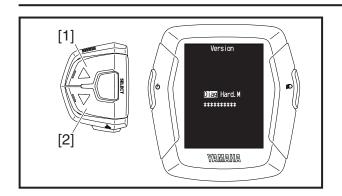


How to delete the malfunction history

- 1. While pressing the light switch [1] during the error code display, press the assist mode switches [2] or [3].
- 2. When the history is deleted, "NO ERROR" is displayed. Press the power switch to turn off the display unit.

TIP.

Be sure to clear the diagnosis history after replacing the motor or other parts.



Firmware ver. check mode

You can confirm the version information for the hardware and firmware of the Drive Unit and meter.

- Enter the firmware ver. check mode.
 See "Operating procedures to self-diagnosis mode".
- 2. Press the assist mode switch [1] or [2] to display the version information for the meter hardware, meter firmware, Drive Unit hardware, and Drive Unit firmware.

TIP_

Detailed version information will be provided from Yamaha separately as needed.

List of firmware ver. check mode display methods

Items	Display
1) Meter hardware version	Version Diag Hard.M *************
2) Meter firmware version	Version Diag Soft.M ***********************************
3) Drive Unit hardware version	Version Diag Hard.DU ***********************************
4) Drive Unit firmware version	Version Diag Soft.DU ***********************************

List of error codes and corresponding assist operation

Error codes	Fault device	Fault details	Restoration condition	Action	
12	Display unit	Stopped the communications to the display unit	If the system will not detect any	Check the display unit connector. Replace the display unit assembly. Replace the wire lead 2. Replace the controller assembly.	
13	Drive Unit - Display unit	Communication data failure to display unit		Make sure that the combination of Drive Unit and display unit are correct.	
		No communication signals			
		Disconnected			
31		Short-circuited	If the system will not detect any	Replace the torque sensor	
		Wiring failure between the torque sensor and the controller	errors, the system can return to normal when the power is	assembly. 2. Replace the controller	
32	Torque sensor	Wiring failure between the coil and the circuit board (wire chattering: nearly disconnect- ed)	cycled.	assembly.	
33	3611301	Abnormal no-load voltage	If the system will not detect any		
34		Abnormal voltage (detected	errors, the system can return to	Perform the torque sensor reference voltage adjust	
35		during running / with high constant voltage)	normal when the power is cycled. (When the system detects same error several times, the	reference voltage adjust- ment. 2. Replace the torque sensor assembly. 3. Replace the controller assembly.	
36		Abnormal voltage (detected during running / others)			
37		Abnormal voltage (detected during running at low speeds)	system can not return to normal even if the power is cycled.)		
38	Crank	Torque sensor or crank sensor failure	If the system will not detect any errors, the system can return to	Replace the torque sensor assembly or controller assembly or drive axle assembly.	
39	sensor	Short-circuited or crank sensor failure	normal when the power is cycled.	Replace the controller assembly or drive axle assembly.	
61	Controller	Abnormal voltage of the sensor for U phase current while the motor is not operating	If the system will not detect any errors, the system can return to	Replace the controller assem-	
61	Controller	Abnormal voltage of the sensor for W phase current while the motor is not operating	normal when the power is cycled.	bly.	
		Over current is applied to the U phase of the motor			
		Over current is applied to the V phase of the motor			
	Motor	Over current is applied to the W phase of the motor	The system can not return to	Replace the controller assembly.	
62	IVIOLOI	Abnormal current is applied to the U phase of the motor	normal even if the power is cycled.		
		Abnormal current is applied to the V phase of the motor			
		Abnormal current is applied to the W phase of the motor			

Error	Fault			
codes	device	Fault details	Restoration condition	Action
63		Failure in data reading	If the system will not detect any	
66		External memory data error	errors, the system can return to normal when the power is	
66		EEPROM error	cycled.	
64	Controller ture	Detected circuit board temperature is too low (–20°C) Detected circuit board temperature is too high (125°C)		Replace the controller assembly.
04		(including DC circuit)	(When the system detects same error several times, the	
		Sensor on the board is nearly detached	system can not return to normal even if the power is cycled.)	
		2 lead wires are disconnected		
		Yellow lead wire is disconnected (U phase)	If the system will not detect any errors, the system can return to	Replace the controller assembly.
67	Motor	Blue lead wire is disconnected (V phase)	normal when the power is cycled.	Replace the wire lead 3 or wire lead 4 or wire lead 5.
		White lead wire is disconnected (W phase)		
68	Encoder	Disconnected or led wire is short-circuited	If the system will not detect any errors, the system can return to normal when the power is cycled.	Check the encoder connector. Replace the encoder lead wire.
00	Encodei	Black wire is short-circuited		3. Replace the controller assembly. 4. Replace the motor assembly.
71	Battery	Can't receive data from battery correctly	If the system will not detect any errors, the system can return to	Replace the plug D.C. receptacle or wire lead 2. Replace the controller assembly. Replace the battery assembly.
73	,	Detected battery voltage is too high (45V)	normal when the power is cycled.	Replace the controller assembly. Replace the battery assembly.
74		Internal system failure		Replace the battery assembly.
79	DC/DC converter	Abnormal DC current	If the system will not detect any errors, the system can return to normal when the power is cycled.	Replace the external DCDC converter. Replace the controller assembly.
-	Speed sensor	Speed sensor disconnected	If the system will not detect any errors, the system can return to normal immediately.	 Check the speed sensor lead connector. Check the gap between the pick up and the magnet sensor. Replace the speed sensor set.
-	Drive Unit - Battery	Communication error between the Drive Unit and the battery	If the system will not detect any errors, the system can return to normal immediately.	Check the battery communication connector. Replace the plug DC. Replace the controller assembly. Replace the battery.

YAMAHA E-KIT DIAGNOSTIC TOOL

This model uses the Yamaha e-kit diagnostic tool to identify malfunctions.

For more information about using the Yamaha e-kit diagnostic tool, refer to the operation manual that is included with the tool.

Functions of the Yamaha e-kit diagnostic tool

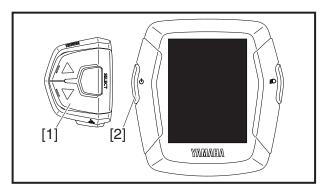
Drive Unit malfunction diagnosis:

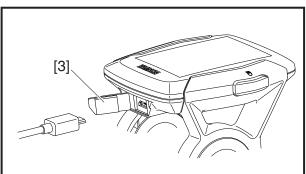
Drive Unit malfunction codes recorded on the controller are read, and the contents are displayed. The freeze frame data (FFD) is the operation data when a malfunction was detected. This data can be used to identify when the malfunction occurred and check the Drive Unit conditions and running conditions when it occurred.

Drive Unit system function test: Check the operation and the output value of each sensor

and actuator.

Battery information: Displays the battery data.





Connecting the Yamaha e-kit diagnostic tool

- Make sure that the power is turned off to the display unit.
- 2. Continue to press the assist mode switch (down) [1] and power switch [2] over 2 sec.
- 3. Confirm that the "Pc" is displayed, and then release the assist mode switch (down) [1] and power switch [2].
- 4. Open the USB receptacle cap [3] of the display.
- 5. Connect the USB cable to the switch and computer with the Yamaha e-kit diagnostic tool.

TIP

- After disconnecting the USB cable, be sure to close the USB receptacle cap [3].
- For the USB cable, use a Type-A to Micro-B cable that is not an OTG cable.
- When the Yamaha e-kit diagnostic tool is connected to the vehicle, the operation of the multifunction meter and indicators will be different from the normal operation.

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